# Matrix Analysis with a Focus on InEQUALITIES 

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## Introduction

## Definition (Symmetric Matrix)

A matrix $A$ is a symmetric matrix if $A^{T}=A$.

## Definition (Orthogonal Matrix)

A square matrix $A$ is an orthogonal matrix if $A^{T}=A^{-1}$.

## Theorem (Spectral Decomposition for Symmetric Matrices)

Let $A$ be an $n \times n$ real symmetric matrix. Let $\lambda_{1}, \ldots, \lambda_{n}$ be its eigenvalues. Let $v_{1}, \ldots, v_{n}$ be corresponding eigenvectors. Then $A=P \Lambda P^{T}$, where $P=\left[v_{1}, \cdots, v_{n}\right]$ and $\Lambda=\operatorname{diag}\left[\lambda_{1}, \cdots, \lambda_{n}\right]$.

## Remark

The matrix $P$ above is an orthogonal matrix.

## Introduction

## Definition (Non-Negative Definite Matrix)

An $n \times n$ real symmetric matrix $A$ is called non-negative definite if $\mathbf{x}^{T} A \mathbf{x} \geq 0$ for all $\mathrm{x} \in \mathbb{R}^{n}$.

## Theorem

An $n \times n$ real symmetric matrix $A$ is non-negative definite if and only if all its eigenvalues are non-negative.

## Definition (Positive Definite Matrix)

An $n \times n$ real symmetric matrix $A$ is called positive definite if $\mathbf{x}^{T} A \mathbf{x}>0$ for all nonzero $\mathrm{x} \in \mathbb{R}^{n}$.

## Theorem

An $n \times n$ real symmetric matrix $A$ is positive definite if and only if all its eigenvalues are positive.

## Introduction

## Example

Let $A$ and $B$ be two $n \times n$ real symmetric positive definite matrices. Let $k_{1}, k_{2} \in \mathbb{R}^{+}$. Let $C=k_{1} A+k_{2} B$. Then $A B^{-1} A, C$ and $C^{-1}$ are all symmetric positive definite matrices.

## Proof.

- Since $A$ is a real symmetric positive definite, we know $A$ is non-singular.
- So it is full rank, which implies that $A$ has a trivial null space.
- Since $B$ is positive definite, $B^{-1}$ is also.
- Then $x^{T}\left(A B^{-1} A\right) x=(A x) B^{-1}(A x)=0$ if and only if $A x=0$, if and only if $x=0$.
- Thus, the matrix $A B^{-1} A$ is positive definite.


## Introduction

## Definition (Matrix Square Root)

Let $A$ be a positive definite matrix. Then the square root of matrix $A$ is $A^{\frac{1}{2}}=P \Lambda^{\frac{1}{2}} P^{-1}$.

## Example

Let $A=\left[\begin{array}{cc}10 & 6 \\ 6 & 10\end{array}\right]$. Then $\lambda_{1}=4$ with $v_{1}=\left[\begin{array}{c}-1 \\ 1\end{array}\right]$ and $\lambda_{2}=16$ with $v_{2}=\left[\begin{array}{l}1 \\ 1\end{array}\right]$. We now have $A=\left[\begin{array}{cc}-1 & 1 \\ 1 & 1\end{array}\right]\left[\begin{array}{cc}4 & 0 \\ 0 & 16\end{array}\right]\left[\begin{array}{cc}-1 & 1 \\ 1 & 1\end{array}\right]^{-1}$.
Thus, $A^{\frac{1}{2}}=\left[\begin{array}{cc}-1 & 1 \\ 1 & 1\end{array}\right]\left[\begin{array}{cc}4 & 0 \\ 0 & 16\end{array}\right]^{\frac{1}{2}}\left[\begin{array}{cc}-1 & 1 \\ 1 & 1\end{array}\right]^{-1}=\left[\begin{array}{ll}3 & 1 \\ 1 & 3\end{array}\right]$.

## Theorem

Let $A$ be a positive definite matrix and let $A^{\frac{1}{2}}$ be its positive square root. Let $A^{-\frac{1}{2}}$ be the inverse of $A^{\frac{1}{2}}$. Then $A^{\frac{1}{2}}$ is symmetric, and

$$
A^{\frac{1}{2}} A^{\frac{1}{2}}=A, \quad A^{\frac{1}{2}} A^{-\frac{1}{2}}=I, \quad A^{-\frac{1}{2}} A^{-\frac{1}{2}}=A^{-1}
$$

## Introduction

## Definition (Hermitian Matrix)

A square matrix $A$ is a Hermitian (or self-adjoint) matrix if $A=A^{*}$, which means it is equal to its own conjugate transpose.

## Example

Let $A=\left[\begin{array}{cc}1 & 2+i \\ 2-i & 2\end{array}\right]$.
Take the complex conjugate: $\left[\begin{array}{cc}1 & 2-i \\ 2+i & 2\end{array}\right]$.
Take the transpose: $\left[\begin{array}{cc}1 & 2+i \\ 2-i & 2\end{array}\right]$.
The matrix $A$ is a Hermitian matrix since $A^{*}=A$.
If $A$ has real entries, then $A$ is Hermitian if and only if it is symmetric.

## Matrix Equality

- We sometimes use rank-k correction when new data is added to a model.
- By using the Woodbury Matrix Identity, we can do a rank-k correction to the inverse of the original matrix in order to compute the inverse of a rank-k correction of some matrix.


## Theorem (Woodbury Matrix Identity)

Let $A, X, R$, and $Y$ be complex matrices with size $n \times n, n \times r, r \times r$, and $r \times n$, respectively. Suppose that $A, R$, and $A+X R Y$ are invertible. Then

$$
(A+X R Y)^{-1}=A^{-1}-A^{-1} X\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}
$$

## Proof.

$(A+X R Y)\left[A^{-1}-A^{-1} X\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}\right]$
$=I+X R Y A^{-1}-X\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}-X R Y A^{-1} X\left(R^{-1}+\right.$
$\left.Y A^{-1} X\right)^{-1} Y A^{-1}$
$=I+X R Y A^{-1}-\left(X+X R Y A^{-1} X\right)\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}$
$=I+X R Y A^{-1}-X R\left(R^{-1}+Y A^{-1} X\right)\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}$
$=I+X R Y A^{-1}-X R Y A^{-1}$
$=I$

## Matrix Equality

## Theorem (Woodbury Matrix Identity)

Let $A, X, R$, and $Y$ be complex matrices with size $n \times n, n \times r, r \times r$, and $r \times n$, respectively. Suppose that $A, R$, and $A+X R Y$ are invertible. Then $(A+X R Y)^{-1}=A^{-1}-A^{-1} X\left(R^{-1}+Y A^{-1} X\right)^{-1} Y A^{-1}$.

## Corollary

Consider the special case that $n=r$ and $X=Y=I$. Then

$$
\begin{aligned}
(A+R)^{-1} & =A^{-1}-A^{-1}\left(R^{-1}+A^{-1}\right)^{-1} A^{-1} \\
& =A^{-1}-A^{-1}\left(A R^{-1}+I\right)^{-1} \\
& =A^{-1}-\left(A R^{-1} A+A\right)^{-1}
\end{aligned}
$$

## Matrix Inequality

## Definition (Gersgorin Disc)

Let $A=\left[a_{i j}\right]$ be a complex $n \times n$ matrix. For $i \in\{1, \ldots, n\}$, let $R_{i}$ be the sum of the absolute values of the non-diagonal entries in the $i$ th row, that is,

$$
R_{i}=\sum_{j=1, j \neq i}^{n}\left|a_{i j}\right| .
$$

The Gersgorin Disc (centered at $a_{i i}$ with radius $R_{i}$ ) is

$$
D_{i}=\left\{z \in \mathbb{C}:\left|z-a_{i i}\right| \leq R_{i}\right\} .
$$

## Theorem (Gersgorin Disc Theorem)

Every eigenvalue of a matrix lies within at least one Gershgorin disc.

## Matrix Inequality

## Example

If $M=\left[\begin{array}{lll}5 & 1 & 3 \\ 3 & 6 & 2 \\ 4 & 3 & 9\end{array}\right]$ then the Gershgorin Discs are:
$D_{1}=\{z \in \mathbb{C}:|z-5| \leq 4\}, D_{2}=\{z \in \mathbb{C}:|z-6| \leq 5\}, D_{3}=\{z \in \mathbb{C}:|z-9| \leq 7\}$.
We can draw the discs for $M$ :


By the theorem, every eigenvalue lies within at least one discs.
The eigenvalues of $M$ are $\{4,2(4+\sqrt{5}), 2(4-\sqrt{5})\}$.

## Matrix Inequality

## Theorem (Gersgorin Disc Theorem)

Every eigenvalue of a matrix lies within at least one Gershgorin disc.

## Proof.

- Let $\lambda$ be an eigenvalue of $A$ with corresponding non-zero eigenvector $x$ and suppose $\left|x_{i}\right| \geq\left|x_{j}\right|$ for all $j \in\{1, \ldots, n\}$.
- We know $A x=\lambda x$. Then

$$
A x=\lambda x \Longrightarrow \sum_{j=1}^{n} a_{i j} x_{j}=\lambda x_{i} \Longrightarrow \sum_{j, j \neq i} a_{i j} x_{j}=\left(\lambda-a_{i i}\right) x_{i} .
$$

- We divide both sides by $x_{i}$ and take absolute value of previous expression:

$$
\left|\lambda-a_{i i}\right|=\left|\sum_{j, j \neq i} a_{i j} \frac{x_{j}}{x_{i}}\right| \leq \sum_{j, j \neq i}\left|a_{i j}\right|\left|\frac{x_{j}}{x_{i}}\right| \leq \sum_{j, j \neq i}\left|a_{i j}\right|=R_{i}
$$

## Theorem

Let $B$ be a $p \times p$ positive definite symmetric matrix and $b>0$. Then

$$
\frac{1}{(\operatorname{det} \Sigma)^{b}} e^{-\frac{1}{2} \operatorname{tr}\left(\Sigma^{-1} B\right)} \leq \frac{1}{(\operatorname{det} B)^{b}}\left(\frac{2 b}{e}\right)^{b p}
$$

for all $p \times p$ positive definite matrix $\Sigma$. The equality holds only for $\Sigma=\frac{1}{2 b} B$.

## Proof.

- Let $B^{\frac{1}{2}}$ be the symmetric square root of $B$. Then

$$
\operatorname{tr}\left(\Sigma^{-1} B\right)=\operatorname{tr}\left(\Sigma^{-1} B^{\frac{1}{2}} B^{\frac{1}{2}}\right)=\operatorname{tr}\left(B^{\frac{1}{2}} \Sigma^{-1} B^{\frac{1}{2}}\right) .
$$

- Let $\lambda_{i}$ be the eigenvalues of $B^{\frac{1}{2}} \Sigma^{-1} B^{\frac{1}{2}}$. Since the matrix is positive definite, $\lambda_{i}>0$ for all $i$.
- $\sum_{i=1}^{p} \lambda_{i}=\operatorname{tr}\left(B^{\frac{1}{2}} \Sigma^{-1} B^{\frac{1}{2}}\right)=\operatorname{tr}\left(\Sigma^{-1} B\right)$
- $\prod_{i=1}^{p} \lambda_{i}=\operatorname{det}\left(B^{\frac{1}{2}} \Sigma^{-1} B^{\frac{1}{2}}\right)=\operatorname{det}\left(\Sigma^{-1} B\right)=\frac{\operatorname{det}(B)}{\operatorname{det}(\Sigma)}$.

Thus, $\operatorname{det}(\Sigma)=\frac{\operatorname{det}(B)}{\prod_{i=1}^{p} \lambda_{i}}$.

## Proof.

$$
\begin{aligned}
\frac{1}{(\operatorname{det} \Sigma)^{b}} e^{-\frac{1}{2} \operatorname{tr}\left(\Sigma^{-1} B\right)} & =\frac{\prod_{i=1}^{p} \lambda_{i}^{b}}{(\operatorname{det} B)^{b}} e^{-\frac{1}{2} \sum_{i=1}^{p} \lambda_{i}} \\
& =\frac{1}{(\operatorname{det} B)^{b}} \prod_{i=1}^{p} \lambda_{i}^{b} e^{-\frac{1}{2} \lambda_{i}} \\
& \leq \frac{1}{(\operatorname{det} B)^{b}} \prod_{i=1}^{p} \sup _{\lambda_{i} \geq 0}\left\{\lambda_{i}^{b} e^{-\frac{1}{2} \lambda_{i}}\right\} \\
& =\frac{1}{(\operatorname{det} B)^{b}} \prod_{i=1}^{p}(2 b)^{b} e^{-\frac{1}{2} \cdot 2 b} \\
& =\frac{1}{(\operatorname{det} B)^{b}}\left(\frac{2 b}{e}\right)^{b p}
\end{aligned}
$$

The equality holds iff $\Sigma=\frac{1}{2 b} B$.

## Remark

By applying the theorem, we can find the maximum likelihood estimators of multivariate normal distribution.

## Matrix Inequality

- The Rayleigh-Ritz theorem is a numerical method of approximating eigenvalues and originated in the context of solving physical boundary value problems.


## Definition (Rayleigh Quotient)

The Rayleigh quotient for a complex Hermitian matrix $A$ and nonzero vector $x$ is defined as

$$
R(A, x)=\frac{x^{*} A x}{x^{*} x}
$$

## Theorem (Rayleigh-Ritz Theorem)

Let $A$ be a $n \times n$ symmetric matrix with eigenvalues $\lambda_{1} \leq \lambda_{2} \leq \ldots \leq \lambda_{n}$. Then for $x \neq 0$,

$$
\begin{gathered}
\lambda_{1} \leq R(A, x) \leq \lambda_{n} \\
\lambda_{n}=\max _{x \neq 0} \frac{x^{T} A x}{x^{T} x}=\max _{\|x\|=1} x^{T} A x . \\
\lambda_{1}=\min _{x \neq 0} \frac{x^{T} A x}{x^{T} x}=\min _{\|x\|=1} x^{T} A x .
\end{gathered}
$$

## Matrix Inequality

## Example

- Let $A=\left[\begin{array}{lll}1 & 1 & 1 \\ 1 & 2 & 2 \\ 1 & 2 & 3\end{array}\right]$.
- Let $x_{1}=\left[\begin{array}{l}1 \\ 2 \\ 3\end{array}\right], x_{2}=\left[\begin{array}{l}4 \\ 5 \\ 6\end{array}\right]$, and $x_{3}=\left[\begin{array}{l}4 \\ 6 \\ 8\end{array}\right]$.
- Then

$$
R\left(A, x_{1}\right)=\frac{x_{1}^{T} A x_{1}}{x_{1}^{T} x_{1}}=\frac{70}{14}=5,
$$

- and

$$
R\left(A, x_{2}\right)=\frac{x_{2}^{T} A x_{2}}{x_{2}^{T} x_{2}}=\frac{382}{77} \approx 4.961
$$

- and

$$
R\left(A, x_{3}\right)=\frac{x_{3}^{T} A x_{3}}{x_{3}^{T} x_{3}}=\frac{584}{116} \approx 5.034 .
$$

These give lower bounds for the largest eigenvalue of $A$ (note $\lambda_{3} \approx 5.049$ ).

## Matrix Inequality

A generalization of the Rayleigh-Ritz Theorem is the Courant-Fischer Theorem.

## Theorem (Courant-Fischer Theorem)

Let $A$ be a symmetric $n \times n$ matrix. Let $\lambda_{1} \leq \ldots \leq \lambda_{n}$ be its real eigenvalues and $v_{1}, \ldots, v_{n}$ be the corresponding eigenvectors. For $1 \leq k \leq n$, let $S_{0}=\{0\}$, $S_{k}=\operatorname{span}\left\{v_{1}, \cdots, v_{k}\right\}$ and $S_{k}^{\perp}$ be the orthogonal complement of $S_{k}$. Then

$$
\lambda_{k}=\min _{\|x\|=1, x \in S_{k-1}^{\perp}} x^{T} A x=\min _{x \neq 0, x \in S_{\frac{1}{k-1}}^{\perp}} \frac{x^{T} A x}{x^{T} x}
$$

## Matrix Inequality

## Proof.

Since $A$ is a symmetric matrix, we can let $A=Q \Lambda Q^{T}$ be the spectral decomposition, where Q is an orthogonal matrix. Thus $\left\|Q^{T} x\right\|=\|x\|$. $x^{T} A x=x^{T} Q \Lambda Q^{T} x=\left(Q^{T} x\right)^{T} \Lambda\left(Q^{T} x\right)$
Thus, we just need to consider the case when $A$ is a diagonal matrix.
Let $A=\left[\begin{array}{ccc}\lambda_{1} & & 0 \\ & \ddots & \\ 0 & & \lambda_{n}\end{array}\right]$.
Then $x^{T} A x=\left[x_{1}, \ldots, x_{n}\right]\left[\begin{array}{ccc}\lambda_{1} & & 0 \\ & \ddots & \\ 0 & & \lambda_{n}\end{array}\right]\left[\begin{array}{c}x_{1} \\ \vdots \\ x_{n}\end{array}\right]=\sum_{i=1}^{n} \lambda_{i} x_{i}^{2}$
Since $A$ is a diagonal matrix, we know $e_{i}$ is an eigenvector corresponding to $\lambda_{i}$.
If $x \in S_{k-1}^{\perp}$, then $x \perp e_{i}$ for $i \in\{1, \cdots, k-1\}$.
Thus $\left\langle x, e_{i}\right\rangle=0$ for $i \in\{1, \ldots, k-1\}$.
Thus $x_{i}=<x, e_{i}>=0$ for $i \in\{1, \ldots, k-1\}$.

## Matrix Inequality

## Proof.

When $\|x\|=1$ and $x \in S_{k-1}^{\perp}$, we have

$$
\begin{aligned}
x^{T} A x & =\sum_{i=1}^{n} \lambda_{i} x_{i}^{2} \\
& =\sum_{i=k}^{n} \lambda_{i} x_{i}^{2} \text { since } x_{1}=\ldots=x_{k-1}=0 \\
& \geq \sum_{i=k}^{n} \lambda_{k} x_{i}^{2} \text { since } \lambda_{1} \leq \lambda_{2} \leq \ldots \leq \lambda_{n} \\
& =\lambda_{k} \sum_{i=1}^{n} x_{i}^{2} \\
& =\lambda_{k}
\end{aligned}
$$

Also, when $x=e_{k}, x^{T} A x=e_{k}^{T} A e_{k}=\lambda_{k}$.
Thus, $\lambda_{k}=\min _{\|x\|=1, x \in S_{k-1}^{\frac{\perp}{-1}}} x^{T} A x$. Similarly, we know $\lambda_{n}=\max _{\|x\|=1} x^{T} A x$.

## Matrix Inequality

## Theorem (Interlocking Eigenvalue Lemma)

Let $A$ be a symmetric $n \times n$ matrix. Let $\lambda_{1} \leq \ldots \leq \lambda_{n}$ be its real eigenvalues.
Let $\mu_{1} \leq \mu_{2} \leq \cdots \leq \mu_{n}$ be the eigenvalues of $A+b b^{T}$, where $b$ is a vector in $\mathbb{R}^{n}$. Then

$$
\lambda_{1} \leq \mu_{1} \leq \lambda_{2} \leq \mu_{2} \leq \cdots \leq \lambda_{n} \leq \mu_{n}
$$

The interlocking eigenvalue lemma compares the eigenvalues of the original matrix with the eigenvalues after adding a rank 1 matrix.

## Example

Let $A=\left[\begin{array}{lll}1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1\end{array}\right]$ and $b=\left[\begin{array}{l}1 \\ 2 \\ 3\end{array}\right]$. Then $A+b b^{T}=\left[\begin{array}{ccc}2 & 2 & 3 \\ 2 & 5 & 6 \\ 3 & 6 & 10\end{array}\right]$.

We have $\lambda_{1}=\lambda_{2}=\lambda_{3}=1$.
By the Interlocking Eigenvalue Lemma, $\mu_{1}=\mu_{2}=1$.
Also,

$$
\mu_{3}=\operatorname{tr}\left(A+b b^{T}\right)-\mu_{1}-\mu_{2}=15
$$

## Matrix Inequality

- In mathematics, an eigenvalue perturbation problem is that of finding the eigenvectors and eigenvalues of a system that is perturbed from one with known eigenvectors and eigenvalues. This is useful for studying how sensitive the original system's eigenvectors and eigenvalues are to changes.


## Theorem (Weyl's Inequality)

Let $A, B$ be $n \times n$ Hermitian matrices such that the eigenvalues of $A, B$ and $A+B$ are $\lambda_{i}(A), \lambda_{i}(B)$ and $\lambda_{i}(A+B)$ arranged in increasing order, respectively. Then for each $k \in\{1,2, \ldots, n\}$.

$$
\lambda_{k}(A)+\lambda_{1}(B) \leq \lambda_{k}(A+B) \leq \lambda_{k}(A)+\lambda_{n}(B)
$$

When $k=1$ we have:

$$
\lambda_{1}(A)+\lambda_{1}(B) \leq \lambda_{1}(A+B) \leq \lambda_{1}(A)+\lambda_{n}(B) .
$$

When $k=n$ we have:

$$
\lambda_{n}(A)+\lambda_{1}(B) \leq \lambda_{n}(A+B) \leq \lambda_{n}(A)+\lambda_{n}(B)
$$

## Matrix Inequality

## Proof.

For any $0 \neq x \in \mathbb{C}^{n}$, by Rayleigh Quotient Theorem, $\lambda_{1}(B) \leq \frac{x^{*} B x}{x^{*} x} \leq \lambda_{n}(B)$. Thus, for any $k \in\{1,2, \ldots, n\}$,

$$
\begin{aligned}
\lambda_{k}(A+B) & =\min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*}(A+B) x}{x^{*} x} \\
& =\min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*} A x}{x^{*} x}+\frac{x^{*} B x}{x^{*} x} \\
& \geq \min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*} A x}{x^{*} x}+\lambda_{1}(B) \\
& =\lambda_{k}(A)+\lambda_{1}(B)
\end{aligned}
$$

## Matrix Inequality

## Proof.

Similarly,

$$
\begin{aligned}
\lambda_{k}(A+B) & =\min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*}(A+B) x}{x^{*} x} \\
& =\min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*} A x}{x^{*} x}+\frac{x^{*} B x}{x^{*} x} \\
& \leq \min _{s_{1}, s_{2}, \ldots, s_{n-k} \in \mathbb{C}^{n}} \quad \max _{x \neq 0, x \perp s_{1}, s_{2}, \ldots, s_{n-k}} \frac{x^{*} A x}{x^{*} x}+\lambda_{n}(B) \\
& =\lambda_{k}(A)+\lambda_{n}(B)
\end{aligned}
$$

Thus,

$$
\lambda_{k}(A)+\lambda_{1}(B) \leq \lambda_{k}(A+B) \leq \lambda_{k}(A)+\lambda_{n}(B) .
$$

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## Thank you!

